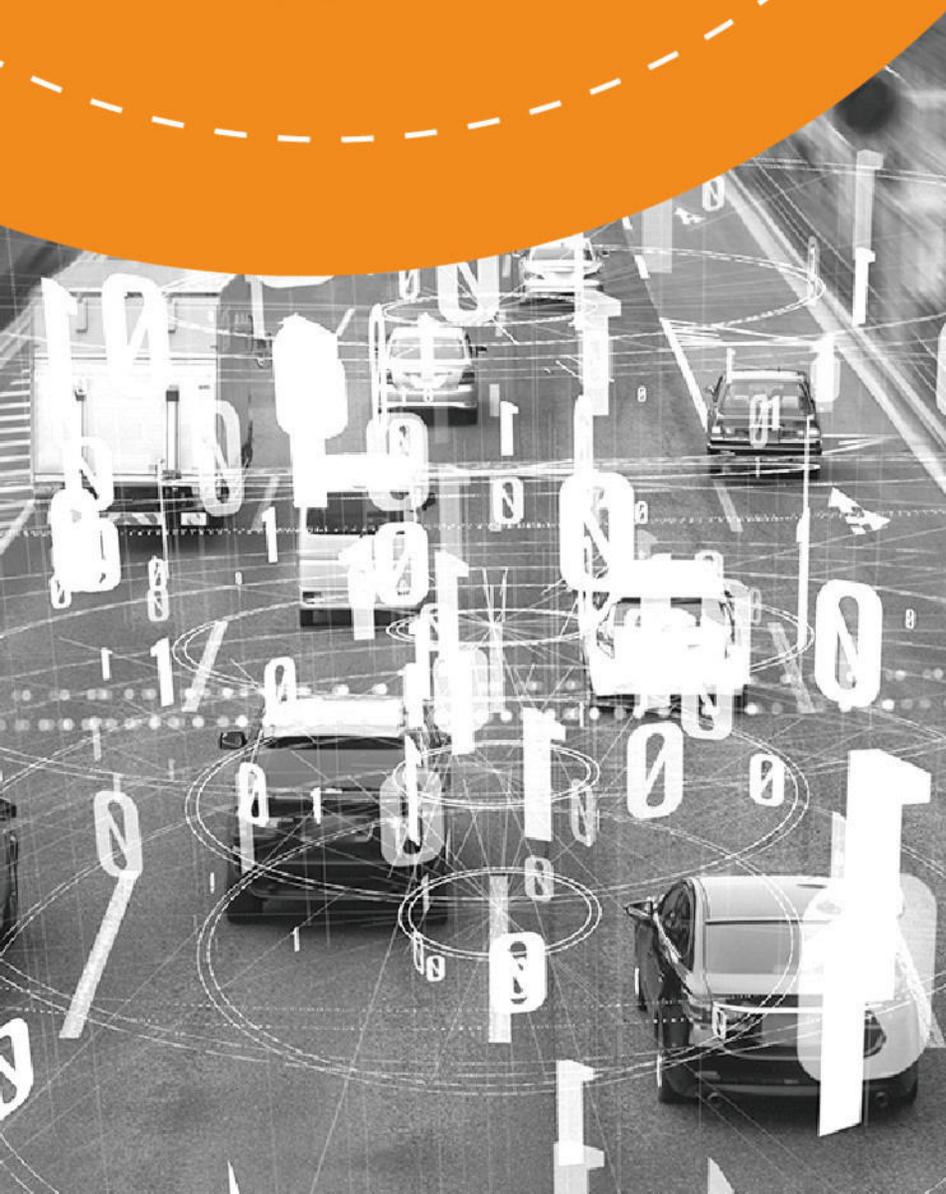
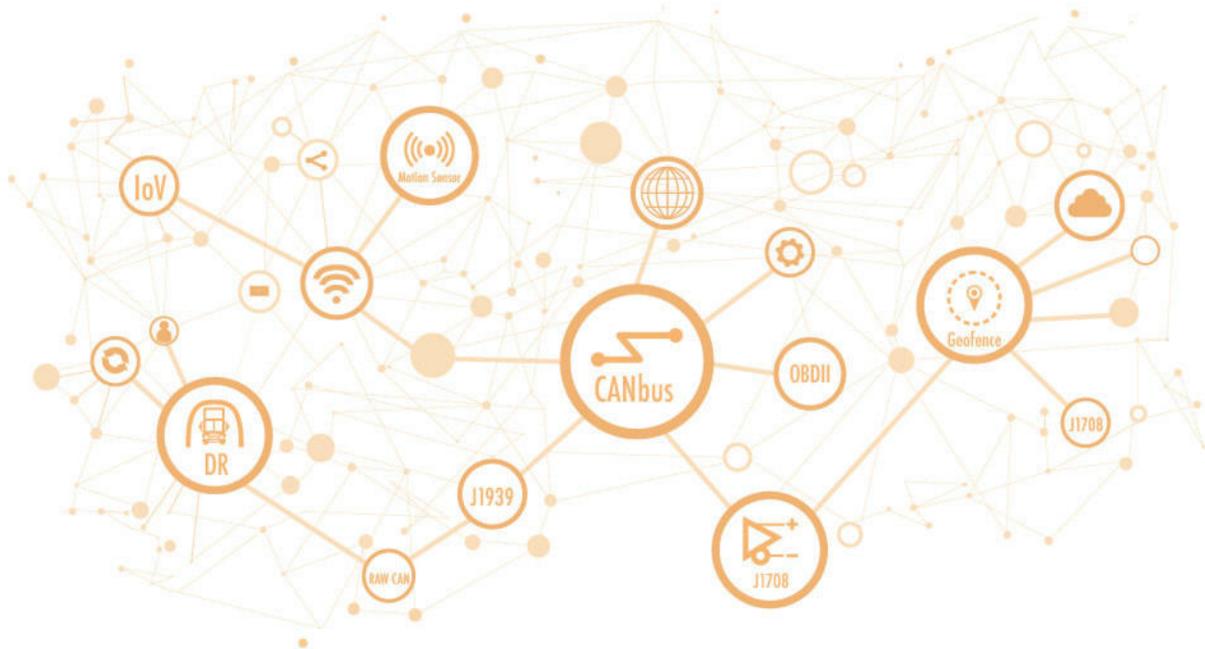


2019

 antzer
Antzer Tech CO., LTD.
DEDICATING IN INTERNET OF VEHICLE



About Antzer Tech



Antzer Tech— a subsidiary of Innodisk Corporation (5289: Taiwan)— aims to provide our partners and customers the most advantageous solution for Fleet Management, Vehicle and Trailer Tracking, Telematics, Vehicle Inspection, and UBI (Usage-based Insurance). The key members in Antzer Tech come from top IPC companies and in-vehicle system providers. Targeting at the rapid growing IoV (Internet of Vehicles) market, Antzer Tech is dedicated to developing CANbus technology. The product of Antzer Tech include CANbus Modules, 3G/4G Cat-1/4G Cat-M1/NB-IoT/LoRa Vehicle Trackers, CANbus and Mobileye® Interpreter, Bluetooth Vehicle Diagnostic Tool, and Vehicle Signal Simulator.

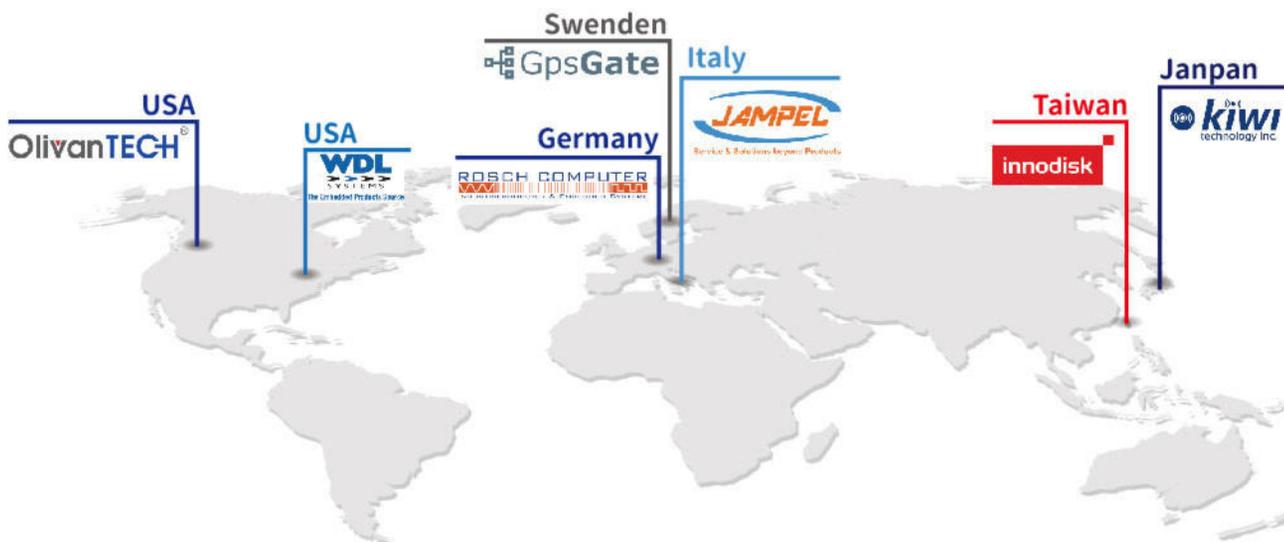
Production



Products of Antzer Tech are manufactured by its parent company, Innodisk Corporation, with industrial-grade factories in Taiwan. The production of our products is in compliance with ISO/TS 16949.

Partners and Distributors

Antzer Tech's clients include industrial computer companies, in-vehicle computer companies, and system integrators of IoV & IoT solutions. The global sales regions extend from Taiwan to United States, Europe, Australia, New Zealand, South and North East Asia.



Fleet Management Solutions

Cost Saving with NB-IoT, Cat-M1 and LoRa

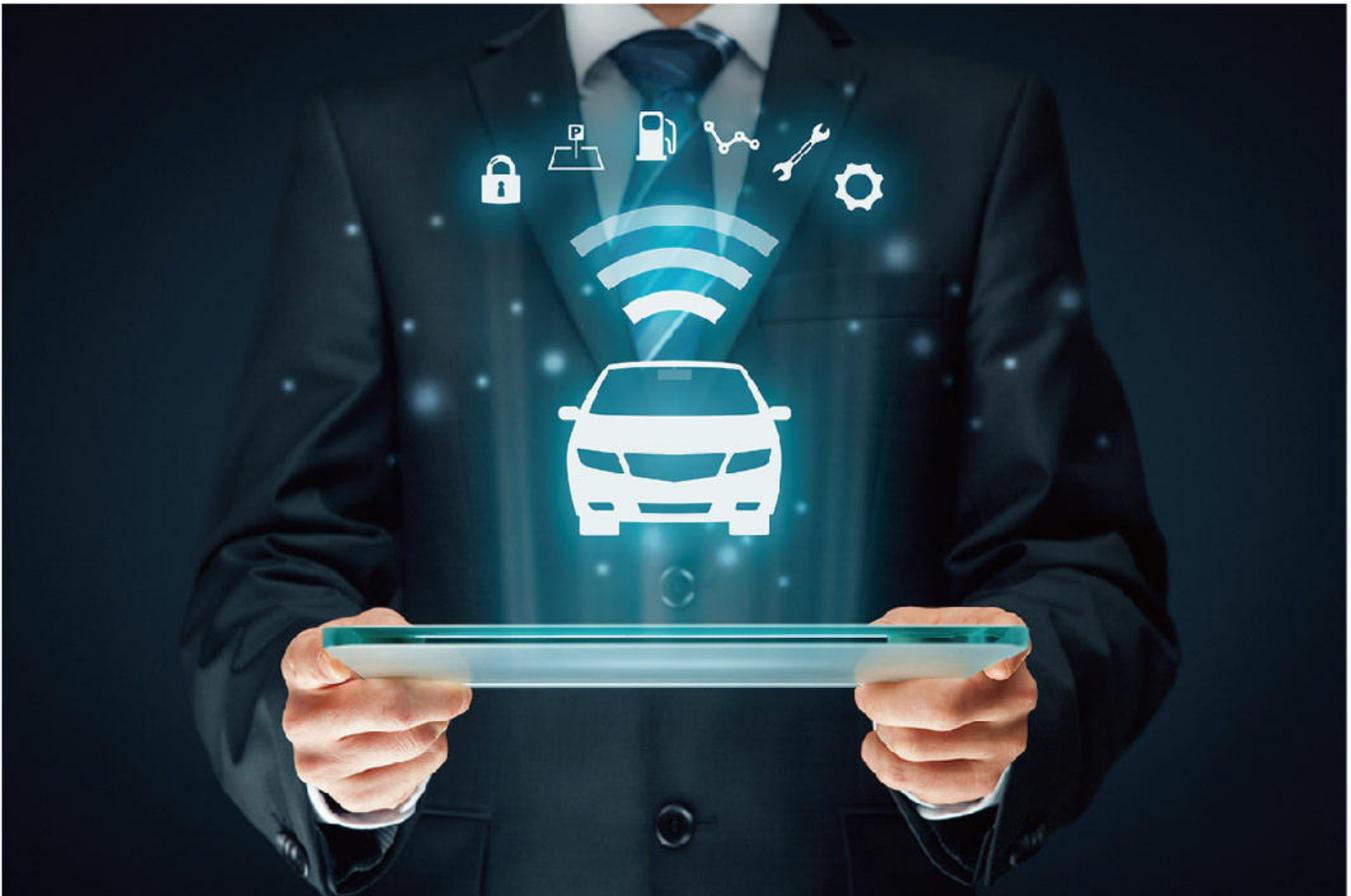
Dead Reckoning Technology for High Accuracy Positioning

Multiple Device Inputs and Outputs for Tracking Vehicle Conditions

Improve Fleet Safety and Driver Behavior

Benefits

- Optimize Fleet Routes
- Lower the Operational Cost
- Speed Up Emergency Response
- Lower the Communication Cost
- Allow Deployment in Wide Area
- Guard the Safety of Drivers and Passengers
- Ideal for Commercial Vehicles and Public Transit

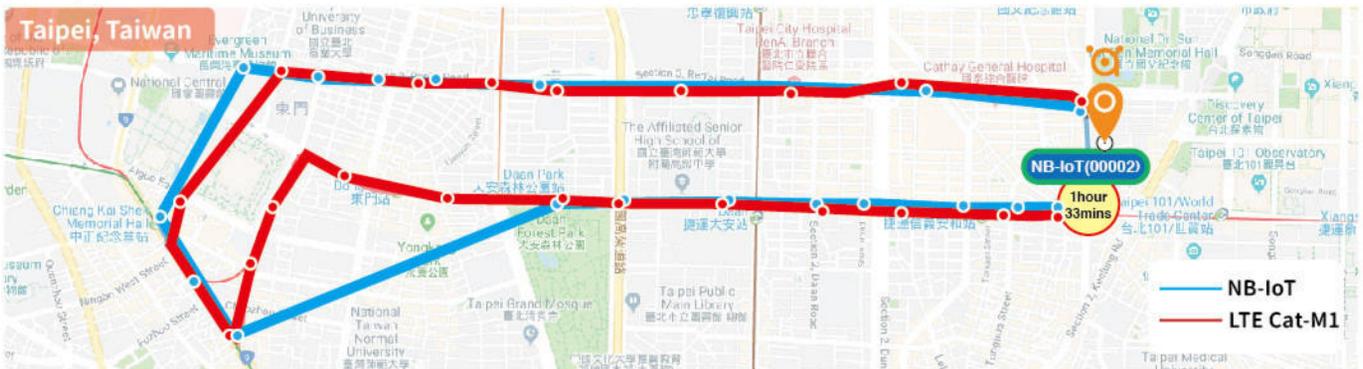


Cost Saving with NB-IoT, Cat-M1 and LoRa

Traditionally, fleet management solutions communicate with cellular networks, such as 3G/4G LTE networks, which could be costly for applications that require only low data transmission. NB-IoT, LTE Cat-M1, and LoRa can greatly reduce the communication fee. With its low power consumption, the battery life can be greatly extended. Utilizing these features, Antzer Tech offers NB-IoT, LTE CAT-M1 and LoRa trackers to connect the fleet to the backend server.

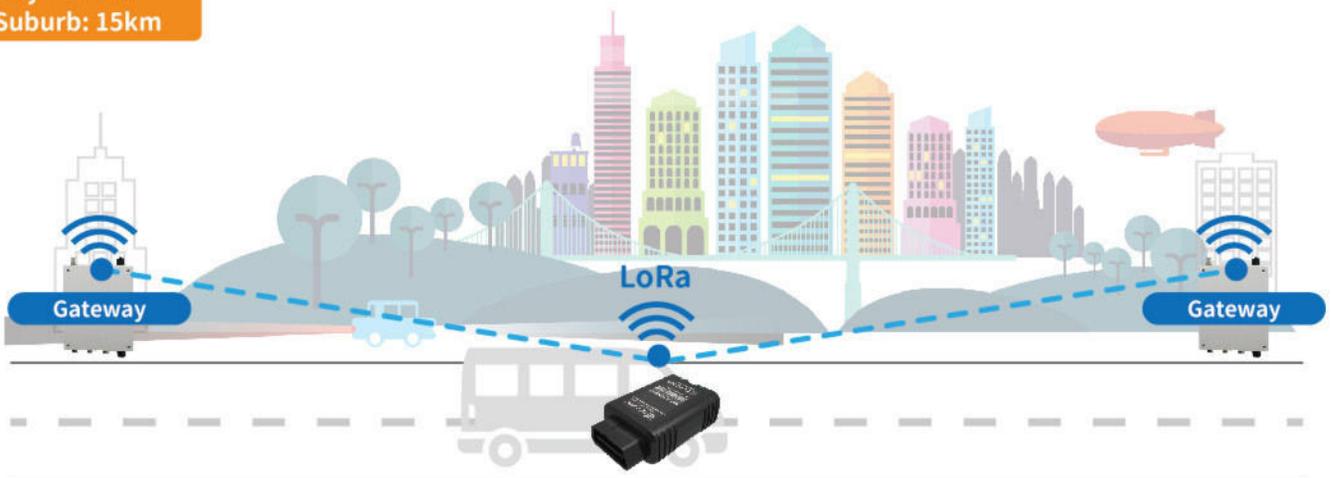
	3G/4G	NB-IoT(R13)	Cat-M1	LoRa
Cellular Monthly Fee	High	Low	Medium	None
Network Type	Public	Public	Public	Private
Coverage (Range, Penetration)	Medium	Wide	Medium	Very Wide
Data Rate	High	Low	Medium	Very Low
Data Transmission Frequency	High	Low	Medium	Low
Latency	Low	High	Medium	High
Packet Size Capacity	High	Low	Medium	Very Low
Power Consumption	High	Low	Medium	Very Low

Comparison of NB-IoT & LTE Cat-M1 Tracker Field Test Results



LoRa Tracker Transmission Range

- City: 2~3km
- Suburb: 15km



Dead Reckoning Technology for High Accuracy Positioning

Positioning Vehicles in Areas with No GPS Signals

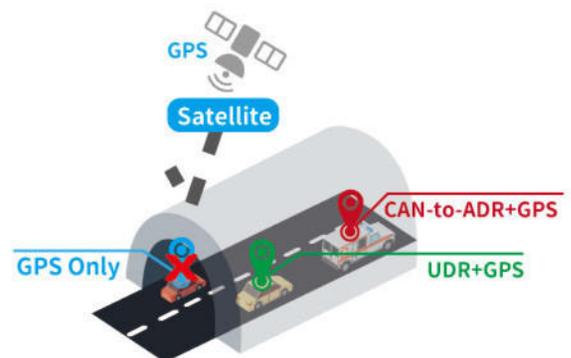
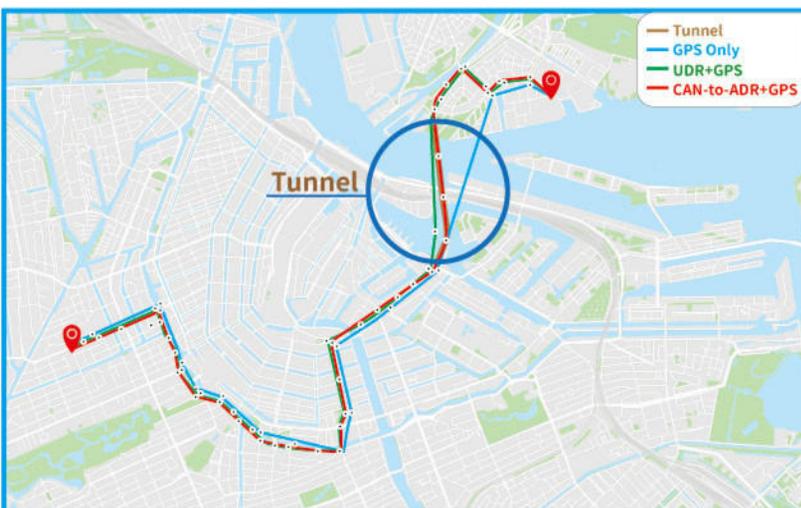
Locating fleet in areas with poor or no GPS signal is challenging. CANbus modules and vehicle trackers with GPS dead reckoning technology enable accurate positioning in signal poor or non-existent locations or environments. Antzer Tech offers three different GPS dead reckoning technology, namely ADR, CAN-to-ADR, and UDR. Of the three, CAN-to-ADR dead reckoning module utilizes Antzer Tech's own patented technology, which calculates position with speed and direction information obtained from CANbus. The feature provides accurate positioning in long tunnel, underground, and dense cities, which is of great value for fleet management applications, such as public transit, armor cash carrier management and high-value asset tracking logistics.

Performance Comparison

Scenarios	GPS	GNSS	UDR	ADR	CAN-to-ADR
Unobstructed Area	●●●	●●●	●●●	●●●	●●●
Suburban area	● ●	●●●	●●●	●●●	●●●
Urban Canyon	●	●	● ●	●●●	●●●
Long Tunnel (e.g. 17 km)	○	○	●	● ●	● ●
Short Tunnel (e.g. < 1 km)	○	○	● ●	●●●	●●●
Error Rate	N/A	N/A	10%	2%	2%

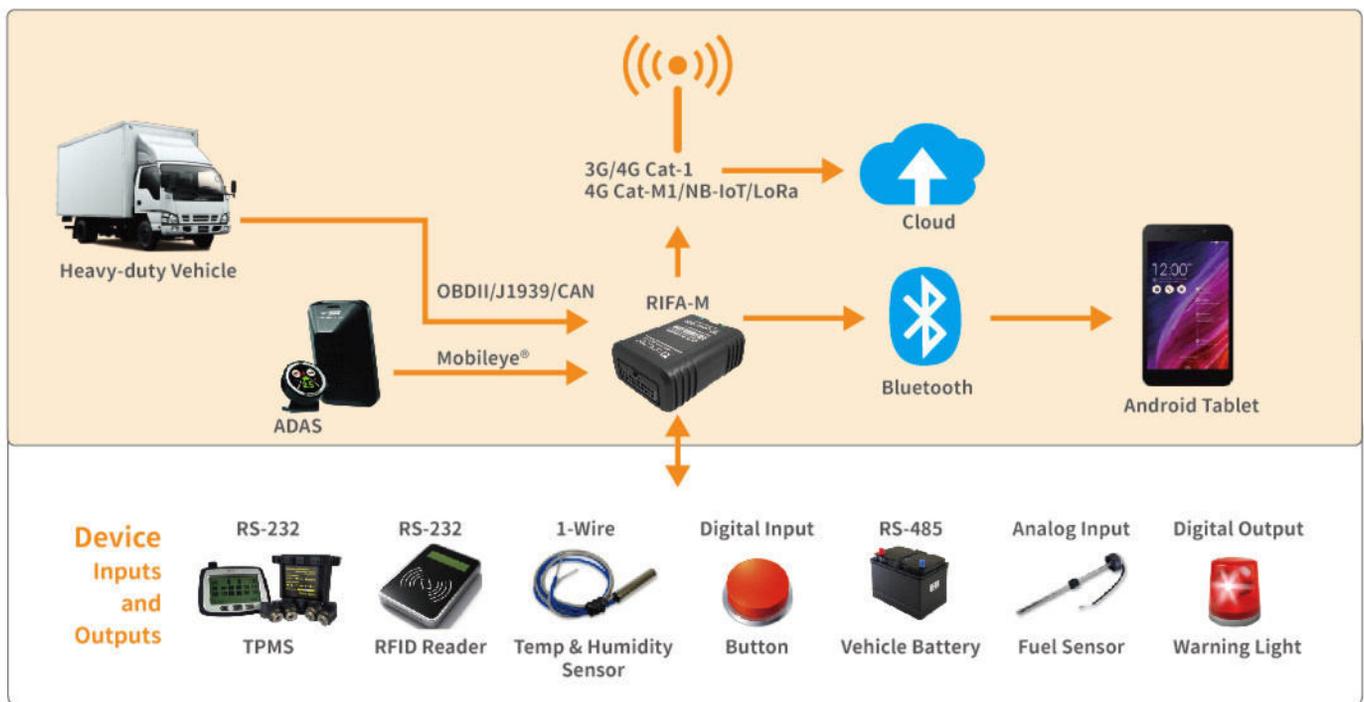
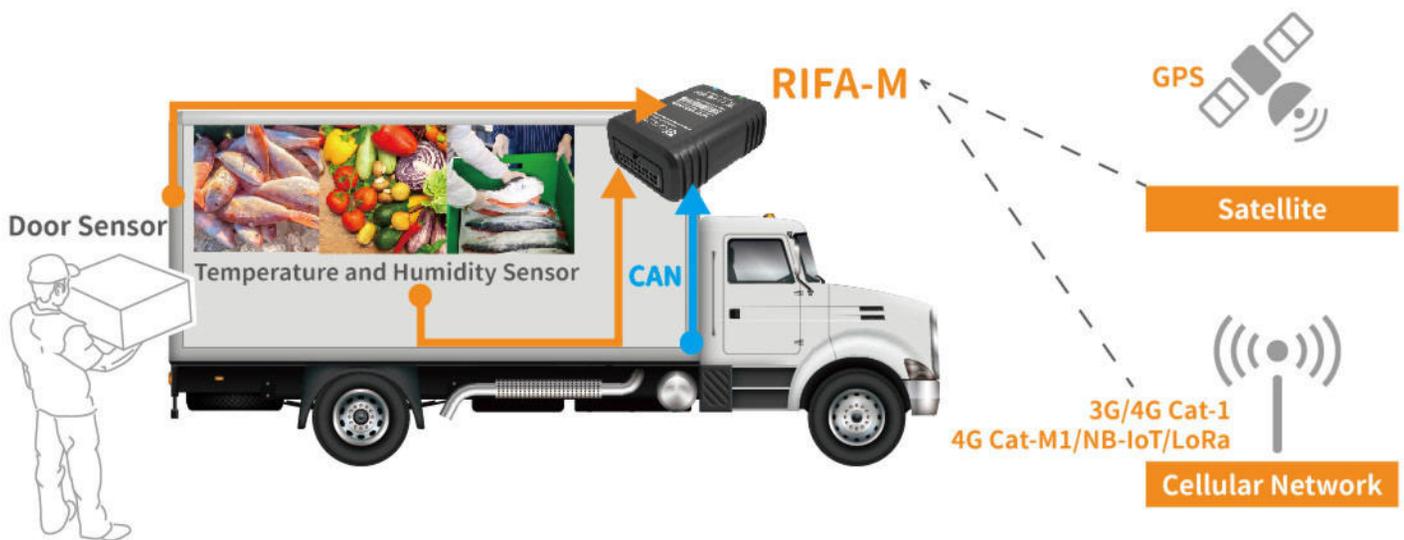
Requirement	GPS	GNSS	UDR	ADR	CAN-to-ADR
Speed and RPM Wheel-tick Information	No	No	No	Yes	Yes
Electrical Connection to The Car	No	No	No	Yes	No

Comparison of GPS, UDR, and CAN-to-ADR



Multiple Inputs and Outputs to Track Vehicle Conditions

When it comes to perishable goods, the environmental condition is crucial during the shipping process. Goods such as fish and vegetables may easily be spoiled or contaminated if the temperature or humidity of the environment during the shipment is mismanaged. Antzer Tech's multifunctional vehicle tracker is equipped with a micro-fit connector that supports additional I/O extensions such as digital input/output, RS-232, 1-wire sensor interface, and two-way voice communication. With an extensional temperature and humidity sensor, the condition of the shipped goods can be closely monitored and therefore the integrity ensured.

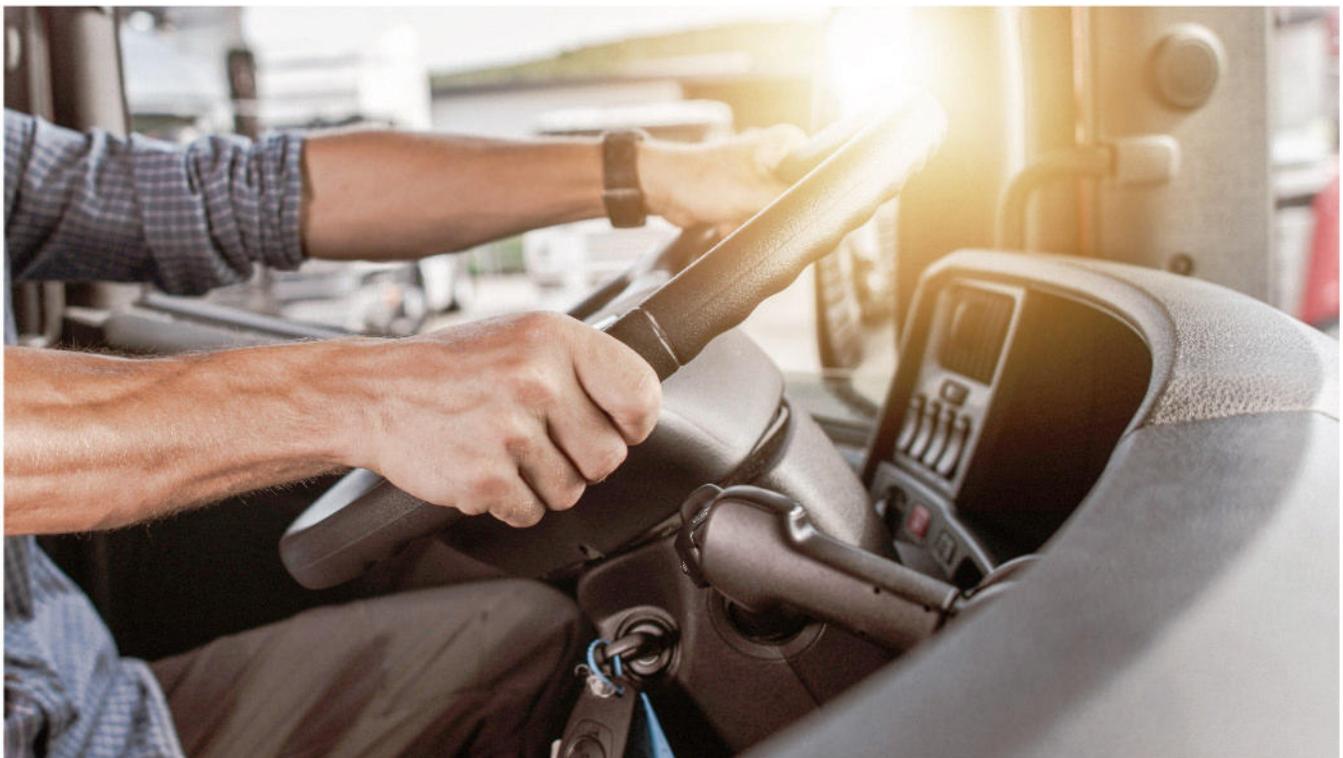


Improve Fleet Safety and Driver Behavior

Driver's behavior is key to driver's safety, vehicle condition, and operational cost. Tracking vehicle speed, driving route, driving time, frequency of harsh-break and harsh-turns helps monitor the real time status of the drivers. The collected data can be analyzed to improve driving habits, to develop optimal routes, and to maintain driving records. Antzer Tech's products acquire vehicle data through Gyro, G-sensor, and CANbus which carries parameters of RAW CAN, OBDII and J1939 protocols.

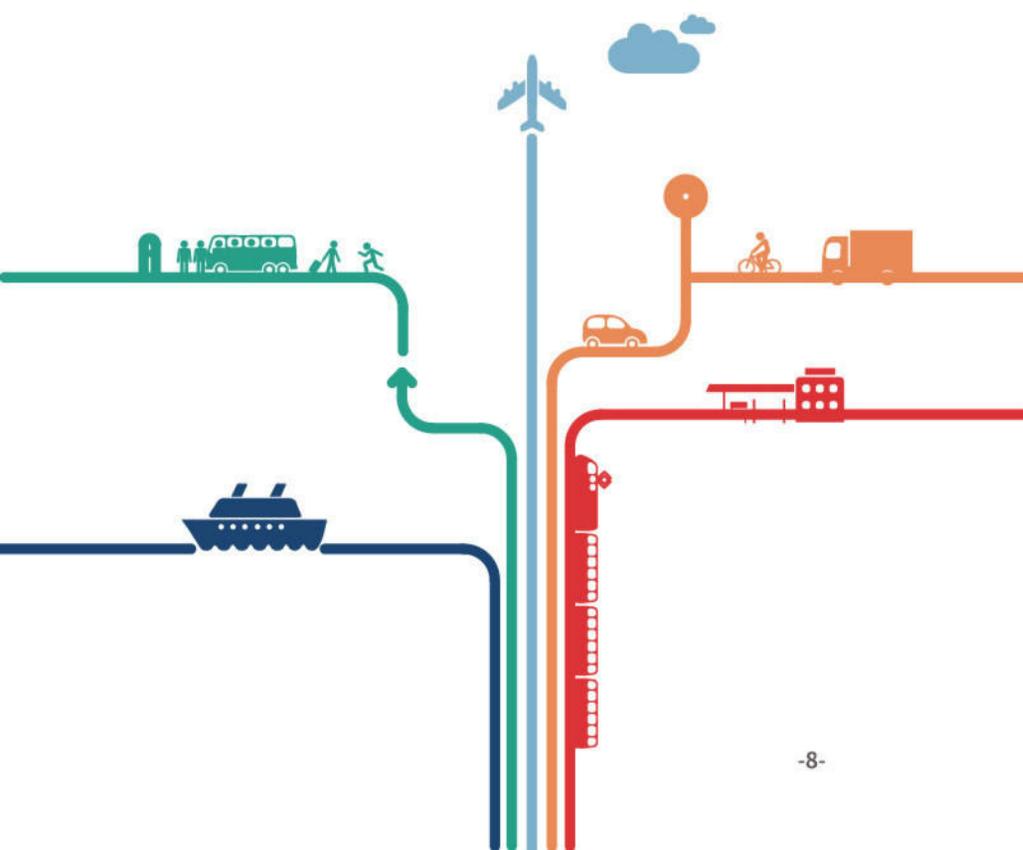
For vehicles installed with Mobileye® ADAS, Antzer Tech's Mobileye® Interpreter transmits all Mobileye® ADAS events and alerts to in-vehicle computers, including Forward Collision Warning, Traffic Sign Recognition, Lane Departure Warning, and etc.

Event Alert	Device	G-Sensor	GPS	Dead Reckoning
Ignition Detection	●			
Low Battery Alert	●			
Removal Alert	●			
Main Power Lost Alert	●			
Crash Detection		●		
Towing Detection		●		
Deviation Angle Event		●		
Harsh Acceleration Event		●		
Harsh Brake Event		●		
Harsh Cornering Event		●		
Total Mileage			●	●
Vehicle Speed			●	●



Product Information

DEDICATING IN INTERNET OF VEHICLE



Product Features

Vehicle CANbus Module



FARO Series

- 2 Ch CANbus and 1 Ch J1708
- Baud Rate Setting: 125/250/500/800/1000Kbps
- RAW CAN, OBDII, J1939 and J1708
- 3D Gyroscope, 3D Accelerometer
- Linux Socket CAN Driver
- Windows & Linux SDK

Vehicle CANbus Module with GPS



GADN Series

- u-blox NEO-M8 GPS
- Navigation During GPS Signal Loss (GPS+DR)
- 2Ch CANbus and 1Ch J1708
- RAW CAN, OBDII, J1939 and J1708
- 3D Gyroscope, 3D Accelerometer
- Windows & Linux SDK



SDK



Linux Socket CAN



GPS
Dead Reckoning
ADR UDR



Dual Channel



CANbus
CAN/OBDII/J1939



J1708



Motion Sensor

Easy Plug Vehicle Tracking Unit



NB-IoT/Cat-M1/LoRa



RIFA-B/RIFA-S Series

- OBDII/J1939
- 3G/4G Cat-1/4G Cat-M1/NB-IoT/LoRa
- Bluetooth 4.2
- Navigation During GPS Signal Loss (GPS+DR)
- Geofence (Polygon Zones)
- Harsh Driving Detection
- FOTA
- Small Size Version Available

Multifunctional Vehicle Tracking Unit



NB-IoT/Cat-M1/LoRa



RIFA-M Series

- RS232/RS485/x2 CAN/1-Wire/x2 DI/x2 DO
- OBDII/J1939
- 3G/4G Cat-1/4G Cat-M1/NB-IoT/LoRa
- Bluetooth 4.2
- Navigation During GPS Signal Loss (GPS+DR)
- Geofence (Polygon Zones)
- Harsh Driving Detection
- FOTA



DR



Geofence



Motion Sensor



FOTA

Product Features

Bluetooth Vehicle Diagnostic Tool



PARA Series

- OBDII/J1939
- Auto Detects CANbus Baud Rate
- 12V/24V Vehicle Power Sources
- Bluetooth 4.2
- Over 17 PIDs/ 20 PGNs (RPM, Fuel level, Odometer, etc.)
- Demo APP for Android Phone

*The product design is tentative. The appearance is subject to change without notice

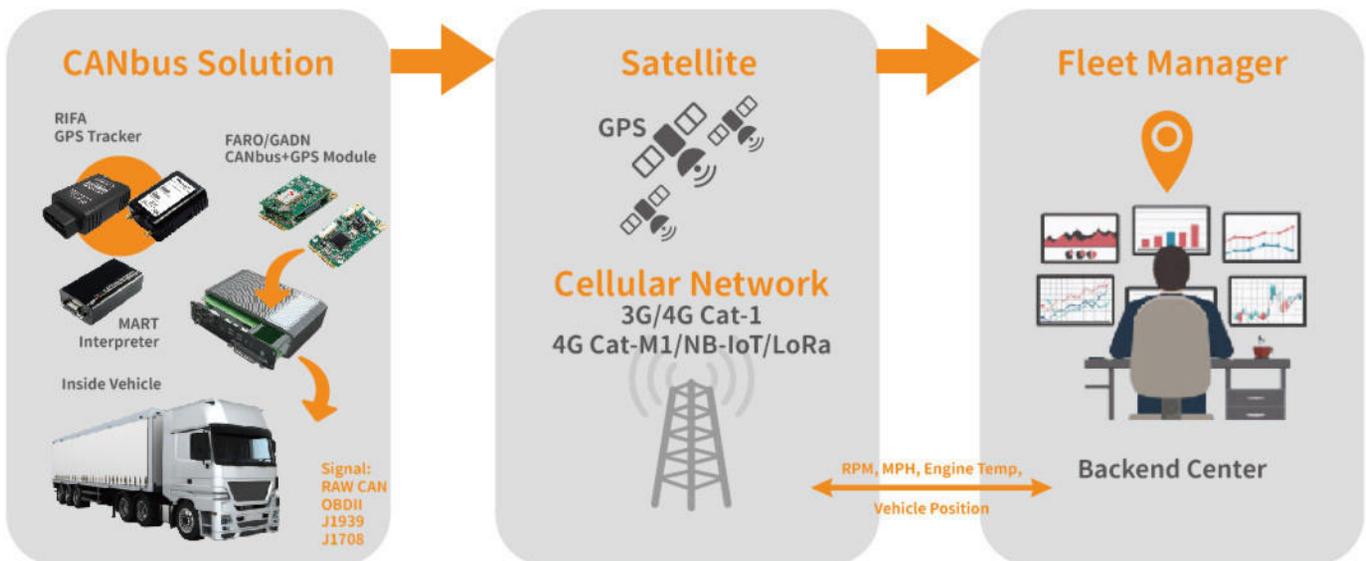


OBDII/J1939/Mobileye® Vehicle Interpreter



MART Series

- OBDII/J1939
- Auto Detects CANbus Baud Rate
- 2 Ch CANbus
- Host Interface: RS232 or USB
- Over 17 PIDs/20 PGNs (RPM, Fuel Level, Odometer, etc.)
- Mobileye® Compatible



Product Catalog

Vehicle CANbus Module

	Series	Part Number	Form Factor		Host Interface	Protocol				Standard GPS	Dead Reckoning	Sensor	Software Support		Operating Temperature	Dimension					
			Half Mini PCIE	Full Mini PCIE		Raw CAN	OBDDII	J1939	J1708				Driver	SDK							
CANbus Module	FARO	FARO-HS100	●			●				N/A	N/A	3-Axis Gyroscope 3-Axis Accelerometer	Microsoft Windows 7 / 8 / 8.1 / 10 Linux Ubuntu 14.04 and Later SocketCAN (Source Code)	Microsoft Windows 7 / 8 / 8.1 / 10 Linux Ubuntu 14.04 and Later	-40°C ~ +85°C	26.8x30x 6.56 mm					
		FARO-FS100		●		●										50.9x30x 6.56 mm					
		FARO-HS700	●		USB 2.0 via PCI Express Mini Card Socket	●	●										26.8x30x 6.56 mm				
		FARO-FS700		●		●	●										50.9x30x 6.56 mm				
		FARO-FS900		●		●	●	●	●								50.9x30x 6.56 mm				
CANbus Module with GPS	GADN	GADN-FS1N0				●				N/A	3-Axis Gyroscope 3-Axis Accelerometer	Microsoft Windows 7 / 8 / 8.1 / 10 Linux Ubuntu 14.04 and Later SocketCAN (Source Code)	Microsoft Windows 7 / 8 / 8.1 / 10 Linux Ubuntu 14.04 and Later	-40°C ~ +85°C	50.9x30x 13.2 mm						
		GADN-FS7N0				●	●	●													
		GADN-FS9N0				●	●	●	●												
		GADN-FS1U0				●										UDR					
		GADN-FS7U0				●	●	●	●												
		GADN-FS9U0	●		USB 2.0 via PCI Express Mini Card Socket	●	●	●	●	●											
		GADN-FS1L0				●										ADR					
		GADN-FS7L0				●	●	●	●												
		GADN-FS9L0				●	●	●	●	●											
		GADN-FG1LR				●										ADR/ CAN-to-ADR					
		GADN-FG9LR				●	●	●	●	●											

Vehicle Tracking Unit

	Series	Part Number	Vehicle Interface	Comprehensive I/O	Network	Frequency Band	Data Protocol	OBDDII	J1939	Mobileye®	G-Sensor	Antenna	GPS	Dead Reckoning	Bluetooth	Battery	Power Supply Input Range	Operating Temperature
Easy Plug GPS Tracker	RIFA-B	RIFA-B33	Built-in OBDDII Connector	N/A	3G	GSM/GPRS: 850,900,1800, 1900 Mhz HSPA/UMTS: 800,850,900, 1700,1900,2100 Mhz	TCP,UDP, MQTT	●		N/A	3-Axis G-sensor	Internal	Ublox M8 Engine, 72 Channels support GPS, Galileo, GLONASS, BeiDou	With options of UDR/ CAN-to-ADR	With the option of Ublox NINA-B1 2.4GHz Low Energy Bluetooth Class 2	With the option of Built-in 3.7V 130mAh Battery Lithium Ion Polymer Battery	9-32V DC Power Input	-30 to 70 °C (Without Battery)
		RIFA-B73						●	●									
		RIFA-B3L						●										
		RIFA-B7L						●	●									
		RIFA-B3M						●	●									
		RIFA-B7M						●	●									
		RIFA-B3R						●	●									
Multifunctional GPS Tracker	RIFA-M	RIFA-M33	CANBus (OBDDII/ J1939)	<ul style="list-style-type: none"> Dual CAN Ports for OBDDII, J1939 or Mobileye® Signal Input <ul style="list-style-type: none"> x1 RS-485 and x1 RS-232 x2 Digital Input and x2 Digital Output (300mA) x1 Analog Input and x1 1-wire Interface x1 Ignition Input Detect, x1 Buzzer Out 	3G	GSM/GPRS: 850,900,1800, 1900 Mhz HSPA/UMTS: 800,850,900, 1700,1900,2100 Mhz	TCP,UDP, MQTT	●		Optionally support Mobileye® Protocol	3-Axis G-sensor	External	Ublox M8 Engine, 72 Channels support GPS, Galileo, GLONASS, BeiDou	With options of UDR/ CAN-to-ADR	With the option of Ublox NINA-B1 2.4GHz Low Energy Bluetooth Class 2	With the option of Built-in 3.7V 130mAh Battery Lithium Ion Polymer Battery	9-32V DC Power Input	-30 to 70 °C (Without Battery)
		RIFA-M73						●	●									
		RIFA-M3L						●	●									
		RIFA-M7L						●	●									
		RIFA-M3M						●	●									
		RIFA-M7M						●	●									
		RIFA-M3R						●	●									
		RIFA-M7R						●	●									

Vehicle Interpreter

	Series	Part Number	Protocol			Host Interface	CAN Interface	Channel	Voltage Range	Material	Operating Temperature	Dimension
			OBDDII	J1939	Mobileye®							
Interpreter	MART	MART-R260 -A0	●	●	●	1x RS232 D-Sub 9-Pin Female or 1x USB Type-A Male	1x D-Sub 9-Pin Male	2 Individual CAN (ISO 11898) Channels	Jumper-selectable 5V DC Input from any of D-Sub (Male) or D-Sub (Female) or USB connector	Aluminum	-20 to +70 °C	77.8 x 44 x 23 mm