# SMA-IMX6

Freescale i.MX 6 ARM Cortex-A9 RISC Module

# **User's Manual**

1<sup>st</sup> Ed – 17 October 2014

## **FCC Statement**

THIS DEVICE COMPLIES WITH PART 15 FCC RULES. OPERATION IS SUBJECT TO THE FOLLOWING TWO CONDITIONS:

(1) THIS DEVICE MAY NOT CAUSE HARMFUL INTERFERENCE.

(2) THIS DEVICE MUST ACCEPT ANY INTERFERENCE RECEIVED INCLUDING INTERFERENCE THAT MAY CAUSE UNDESIRED OPERATION.

THIS EQUIPMENT HAS BEEN TESTED AND FOUND TO COMPLY WITH THE LIMITS FOR A CLASS "A" DIGITAL DEVICE, PURSUANT TO PART 15 OF THE FCC RULES.

THESE LIMITS ARE DESIGNED TO PROVIDE REASONABLE PROTECTION AGAINST HARMFUL INTERFERENCE WHEN THE EQUIPMENT IS OPERATED IN A COMMERCIAL ENVIRONMENT. THIS EQUIPMENT GENERATES, USES, AND CAN RADIATE RADIO FREQUENCY ENERGY AND, IF NOT INSTATLLED AND USED IN ACCORDANCE WITH THE INSTRUCTION MANUAL, MAY CAUSE HARMFUL INTERFERENCE TO RADIO COMMUNICATIONS.

OPERATION OF THIS EQUIPMENT IN A RESIDENTIAL AREA IS LIKELY TO CAUSE HARMFUL INTERFERENCE IN WHICH CASE THE USER WILL BE REQUIRED TO CORRECT THE INTERFERENCE AT HIS OWN EXPENSE.

## A Message to the Customer

## **Customer Services**

Each and every product is built to the most exacting specifications to ensure reliable performance in the harsh and demanding conditions typical of industrial environments. Whether your new device is destined for the laboratory or the factory floor, you can be assured that your product will provide the reliability and ease of operation.

Your satisfaction is our primary concern. Here is a guide to our customer services. To ensure you get the full benefit of our services, please follow the instructions below carefully.

## **Technical Support**

We want you to get the maximum performance from your products. So if you run into technical difficulties, we are here to help. For the most frequently asked questions, you can easily find answers in your product documentation. These answers are normally a lot more detailed than the ones we can give over the phone. So please consult the user's manual first.

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# **1. Getting Started**

## **1.1 Safety Precautions**

### Warning!



Always completely disconnect the power cord from your chassis whenever you work with the hardware. Do not make connections while the power is on. Sensitive electronic components can be damaged by sudden power surges. Only experienced electronics personnel should open the PC chassis.

### Caution!



Always ground yourself to remove any static charge before touching the CPU card. Modern electronic devices are very sensitive to static electric charges. As a safety precaution, use a grounding wrist strap at all times. Place all electronic components in a static-dissipative surface or static-shielded bag when they are not in the chassis.

**Always note** that improper disassembling action could cause damage to the motherboard. We suggest not removing the heatsink without correct instructions in any circumstance. If you really have to do this, please contact us for further support.

## **1.2 Packing List**

Before you begin installing your single board, please make sure that the following materials have been shipped:

- 1 x SMA-IMX6 Risc Module
- 1 x Quick Installation Guide for SMA-IMX6



If any of the above items is damaged or missing, contact your retailer.

## 1.3 Document Amendment History

Revision	Date	Ву	Comment
1st	April 2014		Initial Release

## **1.4 Manual Objectives**

This manual describes in details SMA-IMX6 Single Board.

We have tried to include as much information as possible but we have not duplicated information that is provided in the standard IBM Technical References, unless it proved to be necessary to aid in the understanding of this board.

We strongly recommend that you study this manual carefully before attempting to set up SMA-IMX6 series or change the standard configurations. Whilst all the necessary information is available in this manual we would recommend that unless you are confident, you contact your supplier for guidance.

Please be aware that it is possible to create configurations within the CMOS RAM that make booting impossible. If this should happen, clear the CMOS settings, (see the description of the Jumper Settings for details).

If you have any suggestions or find any errors regarding this manual and want to inform us of these, please contact our Customer Service department with the relevant details.

## 1.5 System Specifications

System	
	Freescale i.MX 6
Processor	Quad Core ARM Cortex-A9 Up to 1.2GHz
	Dual Display
Graphics	HD 1080p Encode and Decode
	2D and 3D Acceleration
Memory	DDR3L 512MB ~ 2GB
Flash	4GB (Up to 64GB) eMMC On-module
Ethernet	10/100/1000 Mbit/sec
USB	2 x USB 2.0 Port (One OTG)
	Parallel LCD 18/24-bit
Display	LVDS Single Channel 18/24-bit
	НОМІ
Image Capture	2 Interfaces (PCAM_CSI)
Interfaces	
Serial	2 x RX/TX (Ser1/3); 2 x UART (Ser0/2)
Additional	Up to 3 PCIex1, MLB150, 12 x GPIOs, SDIO,
Interfaces	SATA eMMC, 2 x SPI, 5 x I2C, 1 x I2S, SPDIF, WDT,
	2 x CAN, JTAG
FRAM	128Kb I2C Interface FRAM (Optional)
Mechanical &	
Environmental	
SW Support	Android
	Linux
Thermal	Industrial Temperature: -40°C to 85°C (800MHz versions)
Power Supply	3V to 5.25V - Operates Directly from Single Level
	Lithium Ion Cells, or Fixed 3.3V or 5V Power Supplies
	Form Factor: 82mm x 50mm
Compliance	Compliance: SMARC (Smart Mobility Architecture)
	Specification by SGET

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## 1.6 Architecture Overview—Block Diagram

The following block diagram shows the architecture and main components of SMA-IMX6.



# 2. Hardware Configuration

## 2.1 Product Overview



## 2.2 Connector List

The following tables list the function of each of the board's connectors.

Connectors		
Label	Function	Note
JSMA1	iMX6 connector	

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## 2.3 Setting Connectors

## 2.3.1 iMX6 connector (JSMA1)



#### \*Default

Signal	PIN	PIN	Signal
		S1	PCAM_VSYNC
PCAM_PXL_CK1	P1	S2	PCAM_HSYNC
GND	P2	S3	GND
PCAM_D0	P3	S4	PCAM_PXL_CK0
PCAM_D1	P4	S5	I2C_CAM_CK
PCAM_DE	P5	S6	CAM_MCK
PCAM_MCK	P6	S7	I2C_CAM_DAT
PCAM_D2	P7	S8	CSI0_CK+
PCAM_D3	P8	S9	CSI0_CK-
GND	P9	S10	GND
PCAM_D4	P10	S11	CSI0_D0+
PCAM_D5	P11	S12	CSI0_D0-
GND	P12	S13	GND
PCAM_D6	P13	S14	CSI0_D1+
PCAM_D7	P14	S15	CSI0_D1-
GND	P15	S16	GND
PCAM_D8	P16	S17	AFB0_OUT / LED1
PCAM_D9	P17	S18	AFB1_OUT / LED2
GND	P18	S19	AFB2_OUT

Signal	PIN	PIN	Signal
GBE_MDI3-	P19	S20	AFB3_IN / VDD_IN MNTR
GBE_MDI3+	P20	S21	AFB4_IN / ADC_IN
GBE_LINK100#	P21	S22	AFB5_IN
GBE_LINK1000#	P22	S23	AFB6_PTIO
GBE_MDI2-	P23	S24	AFB7_PTIO
GBE_MDI2+	P24	S25	GND
GBE_LINK_ACT#	P25	S26	SDMMC_D0
GBE_MDI1-	P26	S27	SDMMC_D1
GBE_MDI1+	P27	S28	SDMMC_D2
GBE_CTREF	P28	S29	SDMMC_D3
GBE_MDI0-	P29	S30	SDMMC_D4
GBE_MDI0+	P30	S31	SDMMC_D5
SPI0_CS1#	P31	S32	SDMMC_D6
GND	P32	S33	SDMMC_D7
SDIO_WP	P33	S34	GND
SDIO_CMD	P34	S35	SDMMC_CK
SDIO_CD#	P35	S36	SDMMC_CMD
SDIO_CK	P36	S37	SDMMC_RST#
SDIO_PWR_EN	P37	S38	AUDIO_MCK
GND	P38	S39	I2S0_LRCK
SDIO_D0	P39	S40	I2S0_SDOUT
SDIO_D1	P40	S41	I2S0_SDIN
SDIO_D2	P41	S42	I2S0_CK
SDIO_D3	P42	S43	I2S1_LRCK
SPI0_CS0#	P43	S44	I2S1_SDOUT
SPI0_CK	P44	S45	I2S1_SDIN
SPI0_DIN	P45	S46	I2S1_CK
SPI0_DO	P46	S47	GND
GND	P47	S48	I2C_GP_CK
SATA_TX+	P48	S49	I2C_GP_DAT
SATA_TX-	P49	S50	I2S2_LRCK
GND	P50	S51	I2S2_SDOUT
SATA_RX+	P51	S52	I2S2_SDIN

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Signal	PIN	PIN	Signal
SATA_RX-	P52	S53	I2S2_CK
GND	P53	S54	SATA_ACT#
SPI1_CS0#	P54	S55	AFB8_PTIO
SPI1_CS1#	P55	S56	AFB9_PTIO
SPI1_CK	P56	S57	PCAM_ON_CSI0#
SPI1_DIN	P57	S58	PCAM_ON_CSI1#
SPI1_DO	P58	S59	SPDIF_OUT
GND	P59	S60	SPDIF_IN
USB0+	P60	S61	GND
USB0-	P61	S62	AFB_DIFF0+
USB0_EN_OC#	P62	S63	AFB_DIFF0-
USB0_VBUS_DET	P63	S64	GND
USB0_OTG_ID	P64	S65	AFB_DIFF1+
USB1+	P65	S66	AFB_DIFF1-
USB1-	P66	S67	GND
USB1_EN_OC#	P67	S68	AFB_DIFF2+
GND	P68	S69	AFB_DIFF2-
USB2+	P69	S70	GND
USB2-	P70	S71	AFB_DIFF3+
USB2_EN_OC#	P71	S72	AFB_DIFF3-
PCIE_C_PRSNT#	P72	S73	GND
PCIE_B_PRSNT#	P73	S74	AFB_DIFF4+
PCIE_A_PRSNT#	P74	S75	AFB_DIFF4-
<key></key>			<key></key>
PCIE_A_RST#	P75	S76	PCIE_B_RST#
PCIE_C_CKREQ#	P76	S77	PCIE_C_RST#
PCIE_B_CKREQ#	P77	S78	PCIE_C_RX+
PCIE_A_CKREQ#	P78	S79	PCIE_C_RX-
GND	P79	S80	GND
PCIE_C_REFCK+	P80	S81	PCIE_C_TX+
PCIE_C_REFCK-	P81	S82	PCIE_C_TX-
GND	P82	S83	GND

Signal	PIN	PIN	Signal
PCIE_A_REFCK+	P83	S84	PCIE_B_REFCK+
PCIE_A_REFCK-	P84	S85	PCIE_B_REFCK-
GND	P85	S86	GND
PCIE_A_RX+	P86	S87	PCIE_B_RX+
PCIE_A_RX-	P87	S88	PCIE_B_RX-
GND	P88	S89	GND
PCIE_A_TX+	P89	S90	PCIE_B_TX+
PCIE_A_TX-	P90	S91	PCIE_B_TX-
GND	P91	S92	GND
HDMI_D2+	P92	S93	LCD_D0
HDMI_D2-	P93	S94	LCD_D1
GND	P94	S95	LCD_D2
HDMI_D1+	P95	S96	LCD_D3
HDMI_D1-	P96	S97	LCD_D4
GND	P97	S98	LCD_D5
HDMI_D0+	P98	S99	LCD_D6
HDMI_D0-	P99	S100	LCD_D7
GND	P100	S101	GND
HDMI_CK+	P101	S102	LCD_D8
HDMI_CK-	P102	S103	LCD_D9
GND	P103	S104	LCD_D10
HDMI_HPD	P104	S105	LCD_D11
HDMI_CTRL_CK	P105	S106	LCD_D12
HDMI_CTRL_DAT	P106	S107	LCD_D13
HDMI_CEC	P107	S108	LCD_D14
GPIO0 / CAM0_PWR#	P108	S109	LCD_D15
GPIO1 / CAM1_PWR#	P109	S110	GND
GPIO2 / CAM0_RST#	P110	S111	LCD_D16
GPIO3 / CAM1_RST#	P111	S112	LCD_D17
GPIO4 / HDA_RST#	P112	S113	LCD_D18
GPIO5 / PWM_OUT	P113	S114	LCD_D19

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Signal	PIN	PIN	Signal
GPIO6 / TACHIN	P114	S115	LCD_D20
GPIO7 / PCAM_FLD	P115	S116	LCD_D21
GPIO8 / CAN0_ERR#	P116	S117	LCD_D22
GPIO9 / CAN1_ERR#	P117	S118	LCD_D23
GPIO10	P118	S119	GND
GPIO11	P119	S120	LCD_DE
GND	P120	S121	LCD_VS
I2C_PM_CK	P121	S122	LCD_HS
I2C_PM_DAT	P122	S123	LCD_PCK
BOOT_SEL0#	P123	S124	GND
BOOT_SEL1#	P124	S125	LVDS0+
BOOT_SEL2#	P125	S126	LVDS0-
RESET_OUT#	P126	S127	LCD_BKLT_EN
RESET_IN#	P127	S128	LVDS1+
POWER_BTN#	P128	S129	LVDS1-
SER0_TX	P129	S130	GND
SER0_RX	P130	S131	LVDS2+
SER0_RTS#	P131	S132	LVDS2-
SER0_CTS#	P132	S133	LCD_VDD_EN
GND	P133	S134	LVDS_CK+
SER1_TX	P134	S135	LVDS_CK-
SER1_RX	P135	S136	GND
SER2_TX	P136	S137	LVDS3+
SER2_RX	P137	S138	LVDS3-
SER2_RTS#	P138	S139	I2C_LCD_CK
SER2_CTS#	P139	S140	I2C_LCD_DAT
SER3_TX	P140	S141	LCD_BKLT_PWM
SER3_RX	P141	S142	LCD_DUAL_PCK
GND	P142	S143	GND

Signal	PIN	PIN	Signal
CAN0_TX	P143	S144	RSVD / EDP_HPD
CAN0_RX	P144	S145	WDT_TIME_OUT#
CAN1_TX	P145	S146	PCIE_WAKE#
CAN1_RX	P146	S147	VDD_RTC
VDD_IN	P147	S148	LID#
VDD_IN	P148	S149	SLEEP#
VDD_IN	P149	S150	VIN_PWR_BAD#
VDD_IN	P150	S151	CHARGING#
VDD_IN	P151	S152	CHARGER_PRSNT#
VDD_IN	P152	S153	CARRIER_STBY#
VDD_IN	P153	S154	CARRIER_PWR_ON
VDD_IN	P154	S155	FORCE_RECOV#
VDD_IN	P155	S156	BATLOW#
VDD_IN	P156	S157	TEST#
		S158	VDD_IO_SEL#



(Using with carrier board REV-SA01)



## 3.1 Download Source code for building Ubuntu image file

Please make a folder for storing the source code first then typing the command below to get started for the source code download.

\$ Sudo apt-get install git
\$ git clone guest@202.55.227.57:freescale/core.git -b SMARC
About password, please check with BCM Sales or PM to get it.

## 3.2 Set up a Linux host for building U-boot & Kernel Image

We support to compile u-boot & Kernel on Ubuntu 12.04 (64bit version), other version of Ubuntu is not currently supported and may have built issues.

Install host packages needed by building code. This document assumes you are using Ubuntu. Not a requirement, but the packages may be named differently and the method of installing them may be different.

sudo apt-get install ia32-libs sudo apt-get install uboot-mkimage

## 3.3 Building up U-boot & Kernel image

You can follow up the steps below to compile the u-boot & Kernel after downloading the source code.

1.Please move to folder "core" then start to compile both the u-boot & Kernel.

~/\$ cd core/

leo@ubuntu:~/imx6\_core\$ ls core leo@ubuntu:~/imx6\_core\$ cd core/ leo@ubuntu:~/imx6\_core/core\$

2.Type the command to compile both u-boot & Kernel.

\$ make rev-sa01 –j number

(**-j number** means multi jobs for more efficiant building, you can add it according to your CPU performance of PC, e.g. mine is "–j16" as below )

leo@ubuntu:~/imx6\_core/core\$ make rev-sa01 -j16

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3. You can find the u-boot(u-boot.bin) & Kernel(ulmage) under folder "core" as below after the compiling is finish.

leo@ubuntu:~/imx6\_core/core\$ ls fsl kernel Makefile u-boot u-boot-quad.bin u-boot-solo.bin uImage

PS: If you would like to use Mfgtool for flashing image file, you must put the file u-boot.bin and ulmage under "~\Image\smarc" for right detected path.



## 3.4 Use MfgTool to flash Ubuntu into onboard eMMC

Manufacturing tool, a successor of ATK, provides a series of new features to power your mass production work. The features like windows style GUI, multiple devices support, explicit status monitoring, versatile functionalities and highly flexible architecture make it a best choice to meet your critical timing, cost and customization requirements. For using Mfgtool to flash image file into onboard eMMC, please follow up the steps below

1. Please turn on the Pin4 of the DIP switch as below into burning mode of Mfgtool.



- 2. Power on the mainboard then plug the cable from OTG socket to PC.
- Click the folder "~\MFG-Tools", e.g. mine is D:\ MFG-REV-SA01\_Image\MFG-Tools"



4. Click the "**MfgLoader.exe**".

Name	Date modified	Туре	Size
퉬 Profiles	1/7/2014 11:27 AM	File folder	
cfg	12/18/2013 10:21	Configuration sett	1 KB
🔕 MfgLoader	9/12/2013 2:08 PM	Application	68 KB
MfgTool	12/26/2013 5:44 PM	Text Document	1 KE
MfgTool2	8/30/2013 3:18 PM	Application	1,693 KE
🚳 MfgToolLib.dll	8/30/2013 3:17 PM	Application extens	569 KE
MfgToolLib.lib	8/30/2013 3:17 PM	LIB File	8 KB

5. Select the MCU option by name, if the MCU of module board is "i.MX6 Solo", please click "**MX6DL Linux Update**", and click "**Linux-ubuntu**" (Ubuntu GUI version) for the OS of flashing, then click "**Run MFG Tool**".

MX6DL Linux Update	10
Linux-ubuntu	÷
Run MFG Tool	_

Or the if the MCU of module board is "i.MX6 Quad core", please click "**MX6Q Linux Update**", and click "**Linux-ubuntu**" (Ubuntu GUI version) for the OS of flashing, then click "**Run MFG Tool**".

	1
Linux-ubuntu	•

6. The second screen will show up after clicking "Run MFG Tool", and please check whether it shows "**HID-compliant device**" as below, if not, please re-check the cable connection and DIP switch setting between mainboard and PC.

Hub 2Port 2	Status Information	
Drive(s):	Successful Operations:	0
HID-compliant device	Failed Operations:	0
HID-compliant device	Failure Rate:	0 %
	Start	Exit

7. Click "**Start**" to flash image file.

Hub 2-Port 2	Status Information	
Drive(s):	Successful Operations:	0
	Failed Operations:	0
HID-compliant device	Failure Rate:	0 %
	Start	Exit

8. It will show "Done" after flashing is finish, then click "Stop" and "Exit" to close the screen.

Hub 4-Port 1	Status Information	1
Drive(s): F:	Eailed Operations	-
Done	Failure Rate:	0.00 %
	Stop	Exit

9. You can also get the information from Terminal (debug port→COM1) after flashing is finish.



## 3.5 Create a bootable SD card with Ubuntu 12.04 file system

Please insert a SD card in the card reader on your Linux host PC

1) Check device node of your SD card by command below.

\$cat /proc/partitions (for example, mine is /dev/sdd as below)

ava	lue@ubu	intu:/	~/test/ltik	)\$ cat	:/proc/partitions
majo	or mino	or #l	blocks nam	ıe	
	_	~	104057600		
1	8	Θ	104857600	sda	
8	8	1	100548608	sda1	
8	8	2	1	sda2	
8	8	5	4305920	sda5	
{	8	48	1000448	sdd	
1	8	49	996352	sdd1	
ava	lue@ubi	intu:	~/test/ltik	)\$	

Create EXT3 partition for SD card

\$ sudo fdisk /dev/sdd

Type the following parameters (each followed by <ENTER>):

d	[delete the previous page	artition]
---	---------------------------	-----------

- n [create a new partition]
- p [create a primary partition]
- 1 [the first partition]
- 20480 [20480x512bytes=10MB, which leaves enough space for the kernel, the boot loader and its configuration data]
- <enter> [using the default value will create a partition that spans to the last sector of the medium]
- w [this writes the partition table to the medium and fdisk exits].
- Format new partition in EXT3 format
   \$sudo umount /dev/sdd1
   \$sudo mkfs.ext3 /dev/sdd1
- Install bootloader on SD card by command below.
   \$ sudo dd if=u-boot-solo.bin(u-boot-quad.bin) of=/dev/sdd bs=1k seek=1 skip=1 conv=fsync
- 4) Install Linux kernel image on SD card by command below.
   \$ sudo dd if=ulmage of=/dev/sdd bs=1M seek=1 conv=fsync
- 5) Please find the Ubuntu file system from the path "CDROM\REV Image\MFG-REV-SA01\_Image\Image\smarc\ ubuntu.tar.bz2" on User`s CD-ROM and copy it to the partition then follow up the command below.

- \$ sudo umount /dev/sdd1
- \$ sudo mount /dev/sdd1 /mnt
- \$ cd /mnt
- \$ sudo tar jxvpf ~/ubuntu.tar.bz2
- \$ cd
- \$ sudo umount /dev/sdd1

The Ubuntu file system content is now on the SD card. You can insert it to mainboard then turn on the DIP switch pin2&3 as below for booting.



## 3.6 Bootloader settings for booting from SD card

1) Please turn on the Pin 2&3 of the DIP switch as below for booting from SD card .



- Insert SD card on SD socket. Connect RS232 cross over cable from COM1 of mianboard to COM port of Host PC.
- 3) Run hyper terminal program on Host PC (teraterm on Windows or minicom on Linux)
- 4) Power on mainboard and press "space" key to get into bootloader menu.

```
U-Boot 2009.08 (Dec 11 2013 - 17:57:30)
CPU: Freescale i.MX6 family TO1.1 at 792 MHz
Thermal sensor with ratio = 178
Temperature: 38 C, calibration data 0x5694e069
mx6q pll1: 792MHz
mx6q pll2: 528MHz
mx6q pll3: 480MHz
mx6q pll8: 50MHz
ipg clock : 6600000Hz
ipg per clock : 6600000Hz
uart clock : 80000000Hz
cspi clock : 6000000Hz
ahb clock : 13200000Hz
axi clock : 198000000Hz
emi_slow clock: 99000000Hz
ddr clock : 39600000Hz
usdhc1 clock : 198000000Hz
usdhe2 clock : 198000000Hz
usdhe2 clock : 198000000Hz
usdhe3 clock : 198000000Hz
usdhe4 clock : 198000000Hz
nfc clock
                : 24000000Hz
Board: i.MX6DL/Solo: SMARC Board: 0x61011 [POR ]
Boot Device: SD
        1 GB
DRAM:
MMC: FSL_USDHC: 0,FSL_USDHC: 1,FSL_USDHC: 2,FSL_USDHC: 3
In:
        serial
Out:
        serial
        serial
Err:
        got MAC address from IIM: 00:00:00:00:00
Net:
FECO [PRIME]
Hit any key to stop autoboot: 0
MX6 Solo SMARC U-Boot >
```

5) Setup boot device

SMARC U-Boot > print

- 6) Set boot device as below
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→ SMARC U-Boot >setenv linux\_cmd 'setenv bootargs \${linux\_bootargs};mmc dev 1;mmc read \${loadaddr} 0x800 0x3000;bootm'

→ SMARC U-Boot > setenv linux\_bootargs 'console=tty0 console=ttymxc0,115200 root=/dev/mmcblk1p1 rootwait rw'

→SMARC U-Boot> saveenv

→SMARC U-Boot> boot

SMARC U-Boot > setenv linux\_cmd 'setenv bootargs \${linux\_bootargs};mmc dev 1;mmc read \${loadaddr} 0x800 0x3000;bootm' SMARC U-Boot > setenv linux\_bootargs 'console=tty0 console=ttymxc0,115200 root=/dev/mmcblklpl rootwait rw' SMARC U-Boot > saveenv

## 3.7 Bootloader settings for booting from onboard eMMC

1) Please turn on the Pin 1 of the DIP switch as below for booting from onboard eMMC.



- Insert SD card on SD socket. Connect RS232 cross over cable from COM1 of mianboard to COM port of Host PC.
- 3) Run hyper terminal program on Host PC (teraterm on Windows or minicom on Linux)
- 4) Power on mainboard and press "space" key to get into bootloader menu.

U-Boot 2009.08 (Dec 11 2013 - 17:57:30) CPU: Freescale i.MX6 family TO1.1 at 792 MHz Thermal sensor with ratio = 178 Temperature: 38 C, calibration data 0x5694e069 mx6q pll1: 792MHz mx6q pll2: 528MHz mx6q pll3: 480MHz mx6q pll8: 50MHz ipg clock : 6600000Hz ipg per clock : 66000000Hz uart clock : 80000000Hz cspi clock : 6000000Hz ahb clock : 132000000Hz axi clock : 198000000Hz emi slow clock: 99000000Hz ddr clock : 396000000Hz usdhcl clock : 198000000Hz usdhc2 clock : 198000000Hz usdhc3 clock : 198000000Hz usdhc4 clock : 19800000Hz : 24000000Hz nfc clock Board: i.MX6DL/Solo: SMARC Board: 0x61011 [POR ] Boot Device: SD DRAM: 1 GB FSL\_USDHC: 0,FSL\_USDHC: 1,FSL\_USDHC: 2,FSL\_USDHC: 3 MMC: serial In: Out: serial Err: got MAC address from IIM: 00:00:00:00:00:00 Net: FECO [PRIME] Hit any key to stop autoboot: 0 MX6 Solo SMARC U-Boot >

5) Setup boot device

SMARC U-Boot > print

- 6) Set boot device as below
- → SMARC U-Boot >setenv linux\_cmd 'setenv bootargs \${linux\_bootargs};mmc dev 3;mmc read \${loadaddr} 0x800 0x3000;bootm'

→ SMARC U-Boot > setenv linux\_bootargs 'console=tty0 console=ttymxc0,115200 root=/dev/mmcblk0p1 rootwait rw'

- →SMARC U-Boot> saveenv
- →SMARC U-Boot> boot

U-Boot > setenv linux\_cmd 'setenv bootargs \${linux\_bootargs};mmc dev 3;mmc read \${loadaddr} 0x800 0x3000;bootm' U-Boot > setenv linux\_bootargs 'console=tty0 console=ttymxc0,115200 root=/dev/mmcblk0p1 rootwait rw' U-Boot > saveenv

## **3.8 Display output application of IMX6**

This section describes how to setup the display output for LVDS, HDMI, VGA of IMX6 module.

1. You can find the file of resolution setup of LVDS&VGA under the

directory "..~/core/kernel/drivers/video/mxc", for LVDS is "ldb.c", and for VGA is " mxc\_lcdif.c".

leo@ubuntu: ~/imx6_core/core/kernel/drivers/video/mxc	leo@ubuntu: ~/imx6_core/core/kernel/drivers/video/mxc
<pre>Leogubuntu: -/imx6_core/kernel/drivers/video/mxc</pre>	<pre>leogubuntu: -/imx6_core/core/kernel/drivers/video/mxc 25 ); 27 Haffine DISPORV_LC0</pre>
<pre>127 128 128 128 129 130 129 130 130 131 13 13 13 13 13 13 13 13 13 13 13 13</pre>	<pre>56 /* BODX480 0 57 Hz , plxel clk 0 27HHz */ 57 *CCAA.4WUAR, 57, B00, 480, 37037, 58 40, 40, 10, 10, 59 20, 10, 60 FB SYNC CLK LAT FALL, 61 FB_YMODE_NONINTERLACED, 62 9, 63 }, 64 { 65 /* BODX490 0 60 Hz , plxel clk 0 32HHz */ 66 **SEINO.4WUAR, 00, 000, 400, 20050, 67 89, 164, 23, 10, 68 11, 10, 69 FB_SYNC CLK LAT FALL, 71 0,</pre>
"ldb.c"	"mxc_lcdif.c"

 You need to fill the resolution parameter(.mode\_str) on the file "rev\_sa01.c" under "~/core/kernel/arch/arm/mach-mx6/smarc/", and the code of First Display is alway in the upper block.

leo@ubuntu: -/imx6_	core/core/kernel/arch/arm/mach-mx6/smarc	
(2) 188 189 190 191 191 192 193 static	<pre>gplo_request(SMARC_LCD_VDD_EN, "Lcd-vdd-rm"); gplo_direction_output(SMARC_LCD_VDD_EN, "); struct ipuv3_fb_platform_data smarc_fb_data[] = {</pre>	
194 195 196 197 198 199 200 201 201 202	<pre>{     disp_dev = %:cd:,     interface_ptx_fnt = IPU_PIX_FNT_RGB24,     mode_str = %:cd_inden*, /* Eco_inden*, Eco_wvca */     default_bop = %?;     int_clk = Urue,     }; </pre>	First Display
204 204 205 206 207 207 208 209 210 211 211	<pre>{     .disp_dev = "140",     .literface_pix_fmt = IPU_PIX_FMT_BGR24,     .mode_str = "NVVA",     .default_bpp = 10,     .lit_cite = false,     .lite_int = false,     ., };</pre>	Second Display
2445 214 215 215 216 217 218 221 222 224 224 224 224 224 224 224 224	/* { .disp_dev = "lcd", .interface_pix_Tmt = IPU_PIX_FMT_BGR24, .mode_str = "LCD_XGA", .default_bpp = 164, .int_clk = false,	4

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3. Finally, you should fill the parameter for booting on the file "**mx6\_smarc.h**" under the directory "~/core/u-boot/include/configs/".

Please add "video=mxcfb0:dev=**display name**" on the column 132 "rootwait rw \0" to enable display output function when booting.

100						
103						
104						
105						
106						
107						
108	#define CONFIG LOADADDR 0x10800					
100						
110						
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111						
112						
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114						
115						
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110						
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124						
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120						
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129						
130						
131	<pre>_/dev.tenct</pre>	1 kint -				
132	rootwalt rie Vi		db \0-			
133	"House second second open	rds STELMIX DOOLALDST				
134						
125						
135						
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4. Please refer ch1.3 to re-build the u-boot &Kernel binary file for booting.



**Note:** If you need to use double display output in Ubuntu, you should setup the " **rev\_sa01.c**" file first then add the content "video=mxcfb0:dev=first display name

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video=mxcfb1:dev=**second display neme**" to **mx6\_smarc.h**, but for this application, you also need to write a program for controling the second diplay first or the second display will not enable after you follow up all the setting above.

## 3.9 Download Android Source Code for building image file

Please make a folder for storing the source code first then typing the command below to get started for the source code download.

\$ sudo apt-get install git

<u>\$ git clone guest@202.55.227.57:freescale/imx6/Android.git</u> -b 4.4.2-SMARC About password, please check with BCM Sales or PM to get it.

## 3.10 Set up for building Android image file

We support to compile u-boot & Kernel on Ubuntu 12.04 (64bit version), other version of Ubuntu is not currently supported and may have built issues.

Install host packages needed by building code. This document assumes you are using Ubuntu. Not a requirement, but the packages may be named differently and the method of installing them may be different.

- 1) Please follow up the commands below to install "Oracle JDK6.0" first for building up Android image file.
- \$ sudo apt-get install python-software-properties
- \$ sudo add-apt-repository ppa:webupd8team/java
- \$ sudo apt-get update
- \$ sudo apt-get install oracle-java6-installer
- 2) Please follow up the commands below to install the necessary package for build image file.

\$ sudo apt-get install git-core gnupg flex bison gperf build-essential \ zip curl libc6-dev libncurses5-dev x11proto-core-dev \ libx11-dev:i386 libreadline6-dev:i386 \ libgl1-mesa-dev g++-multilib mingw32 openjdk-6-jdk tofrodos \ python-markdown libxml2-utils xsltproc zlib1g-dev:i386 \ ia32-libs u-boot-tools minicom lib32ncurses5-dev \

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## 3.11 Building up Android image file

You can follow up the steps below to compile Android image file after download the source code.

1. Please move to the folder "Android" then start to compile image file.

leo@ubuntu:~/imx6_Android\$ ls
Android
leo@ubuntu:~/imx6_Android\$ cd Android/
leo@ubuntu:~/imx6 Android/Android\$

2. Type the command to compile image file.

```
$ ./run.sh –j16
```

(**-j number** means multi jobs for more efficiant building, you can add it according to your CPU performance of PC, e.g. mine is "–j16" as below ).

~/imx6\_Android/Android\$ ./run.sh -j16

- 3. You can find the finished image file(**u-boot-6q.bin**, **u-boot-6solo.bin**, **system.img**, **recover.img**, **boot.img**) as below after compiling on the directory
  - ~/Android/out/target/product/smarc.

leo@ubuntu:	:~/	Lmx6	And	roid/Androi	id/ou	ut/1	target,	/product/smarc\$ ls -al
total 31410	50							
drwxrwxr-x	9	leo	leo	4096	Jan	2	23:44	
drwxrwxr-x	3	leo	leo	4096	Jan	2	22:09	
- FW- FW- F	1	leo	leo	12	Jan	2	22:47	android-info.txt
- FW-FF	1	leo	leo	4784128	Jan	2	23:34	boot.img
- rw- rw- r	1	leo	leo	29030	Jan	2	22:45	clean_steps.mk
drwxrwxr-x	4	leo	leo	4096	Jan	2	23:36	data
- rw-rw-r	1	leo	leo	53886	Jan	2	23:44	installed-files.txt
-rwxr-xr-x	1	leo	leo	4593124	Jan	2	22:52	kernel
drwxrwxr-x	14	leo	leo	4096	Jan	2	23:44	obj
- <b>r</b> w - <b>r</b> w - <b>r</b>	1	leo	leo	373	Jan	2	22:45	previous_build_config.mk
- FW- FW- F	1	leo	leo	186407	Jan	2	23:34	ramdisk.img
- FW- FW- F	1	leo	leo	701522	Jan	2	23:34	ramdisk-recovery.img
drwxrwxr-x	3	leo	leo	4096	Jan	2	23:34	recovery
- FW- F F	1	leo	leo	5298176	Jan	2	23:34	recovery.img
drwxrwxr-x	8	leo	leo	4096	Jan	2	23:33	root
drwxrwxr-x	5	leo	leo	4096	Jan	2	23:33	symbols
drwxrwxr-x	12	leo	leo	4096	Jan	2	23:33	system
- rw - r r	1	leo	leo	293601280	Jan	2	23:44	system.img
drwxrwxr-x	3	leo	leo	4096	Jan	2	23:19	test
- FWXF - XF - X	1	leo	leo	445804	Jan	2	22:47	u-boot-6q.bin
-rwxr-xr-x	1	leo	leo	445556	Jan	2	22:46	u-boot-6solo.bin
- rwxr - xr - x	1	leo	leo	445804	Jan	2	22:47	u-boot.bin
-rwxr-xr-x	1	leo	leo	4593188	Jan	2	22:52	uImage
- <b>r</b> w - <b>r r</b>	1	leo	leo	134217728	Jan	2	23:37	userdata.img

PS: If you would like to use **Mfgtool** for flashing image file, you must put all the files **u-boot-6q.bin**, **u-boot-6solo.bin**, **system.img**, **recover.img**, **boot.img** under "~\Image\smarc\android" for right detected path.

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- 10	-				
🔆 Favorites	Name	Date modified	Туре	Size	
📃 Desktop	6 boot	1/2/2014 3:25 PM	Disc Image File	4,672 KB	
鷆 Downloads	🙆 recovery	1/2/2014 3:26 PM	Disc Image File	5,174 KB	
E Recent Places	🕑 system	1/2/2014 3:35 PM	Disc Image File	286,720 KB	
	u-boot-6q.bin	1/2/2014 11:52 AM	BIN File	436 KB	
对 Libraries	📄 u-boot-6solo.bin	1/2/2014 11:52 AM	BIN File	436 KB	
Documents					
👌 Music					
E Pictures					
Videos					
📮 Computer					
🛍 Network					

## 3.12 Use MfgTool to flash Android into onboard eMMC

Manufacturing tool, a successor of ATK, provides a series of new features to power your mass production work. The features like windows style GUI, multiple devices support, explicit status monitoring, versatile functionalities and highly flexible architecture make it a best choice to meet your critical timing, cost and customization requirements. For using Mfgtool to flash image file into onboard eMMC, please follow up the steps below

1) Please turn on the **Pin4** of the DIP switch as below into burning mode of Mfgtool.



- 2) Power on the mainboard then plug the cable from OTG socket to PC.
- Select the right folder by MCU name, if the MCU of module board is "i.MX6 Solo", please click the folder "~\ MX6DL-IMX6" to flash image file, e.g. mine is D:\ MFG-REV-SA01\_Image\MX6DL-IMX6"

```
MFG-REV-SA01_Image MX6DL-IMX6
```

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On the other hand, if the MCU of module board is "**i.MX6 Quad core**", please click the folder "~\ **MX6Q-IMX6**" to flash image file, e.g. mine is D:\ MFG-REV-SA01\_Image\ **MX6Q-IMX6**"

MFG-REV-SA01\_Image MX6Q-IMX6

4) Click "MfgTool2.exe" to flash image file into smarc module.

Name	Date modified	Туре	Size
길 Document	1/7/2014 11:27 AM	File folder	
퉬 Profiles	1/7/2014 11:27 AM	File folder	
퉬 Utils	1/7/2014 11:27 AM	File folder	
🚺 cfg	9/18/2013 3:54 PM	Configuration sett	1 KB
📄 i.MX 6 DQ Profiles Included readme	1/17/2013 2:42 AM	Text Document	2 KB
InternalParam	1/6/2014 4:52 PM	Configuration sett	1 KB
MfgTool	1/6/2014 4:53 PM	Text Document	2 KB
MfgTool2 release notes	11/22/2012 6:27 AM	Text Document	3 KB
📔 MfgTool2 user guide	11/22/2012 6:27 AM	Text Document	4 KB
MfgTool2	12/18/2012 8:39 PM	Application	1,661 KB
MfgToolLib.dll	12/18/2012 8:39 PM	Application extens	600 KB
🗊 UICfg	12/18/2012 8:39 PM	Configuration sett	1 KB

5) Click "Start" to flash image file.

Hub 2Port 2 Drive(s):	Status Information Successful Operat	0
	Failed Operations:	0
HID-compliant device	Failure Rate:	0 %
	Start	Exit

6) It will show "Done" after flashing is finish, then click "Stop" and "Exit" to close the screen.

Hub 2Port 2	Status Information	
Drive(s): I:	Successful Operations:	1
	Failed Operations:	0
Done	Failure Rate:	0.00 %
	Stop	Exit

7) You can also get the information from Terminal (debug port $\rightarrow$ COM1) after flashing is finish.



